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Microprocessor-Based Wind Speed and Direction Monitor

Tracy M. Kulpa

Indiana University - Purdue University Fort Wayne

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MICROPROCESSOR-BASED
WIND SPEED AND DIRECTION MONITOR

Final Report

Submitted to Thomas Laverghetta
Professor
Electrical Engineering Technology

Prepared by
Tracy M. Kulpa
May 1, 1991

TABLE OF CONTENTS

List of Figures.....	ii
List of Tables.....	iii
Abstract.....	iv
1.0 Introduction.....	1
1.1 Statement of the Problem.....	1
1.2 Objective of the Report.....	1
1.3 Plan of Procedure for the Report.....	2
2.0 Anemometer.....	2
2.1 Two Assumptions About the Anemometer Internal Components.....	3
2.2 The Actual Components In the Anemometer.....	4
2.3 The Modifications Made to the Anemometer.....	4
3.0 Electrical Hardware.....	5
3.1 Wind Speed.....	6
3.1.1 The Comparator Circuit.....	6
3.1.2 Frequency To Voltage Converter Circuit.....	7
3.1.2.1 Method Used to Calibrate the Wind Speed.....	8
3.1.2.2 Analysis of Data.....	9
3.1.3 Analog To Digital Converter Circuit.....	13
3.2 Wind Direction Analog to Digital Converter Circuit.....	13
3.3 Microprocessor.....	14
3.4 Display.....	15
4.0 Software.....	15
5.0 Conclusion.....	16
6.0 References.....	17
Appendix A: Proposal.....	18
Appendix B: Anemometer Description.....	26
Appendix C: Anemometer Process Description.....	31
Appendix D: Design Calculations and Formulas.....	36
Appendix E: Schematic Diagram and Data Sheets.....	42
Appendix F: Summary of Project Cost.....	69

List of Figures

Figure 1: The Anemometer.....	3
Figure 2: Electrical Hardware Block Diagram.....	5
Figure 3: Unconditioned Pulse Versus Conditioned Pulse.....	7
Figure 4: Frequency versus Miles Per Hour Graph.....	12

List of Tables

Table 1: Calibration of Wind Speed Data (1st Set of Data).....	10
Table 2: Calibration of Wind Speed Data (2nd Set of Data).....	11

ABSTRACT

This report is an overview of what has been completed for Senior Design Phase I and II. The project that I proposed is to design and build a microprocessor-based wind speed and direction monitor. There is a need for this device for someone, such as a sailor. The sailor needs to know wind speed and direction to decide if conditions are right to sail and if so, to determine which direction to point the boat when leaving the shore.

Three major sections are discussed. First, the anemometer used as the mechanical hardware. The internal components of the anemometer are analyzed and the necessary modifications are discussed. Following the mechanical hardware is the electrical hardware.

The wind speed signal that is generated by the tachometer must first go through the comparator circuit, to the frequency to voltage converter circuit, to the analog to digital converter, and finally to the microprocessor. While the wind direction only has to go through an analog to digital circuit before going to the microprocessor. The microprocessor, a Hitachi 63P01, has the software, the final section of this report, on the 2764 EPROM which decodes the signal and outputs to a display.